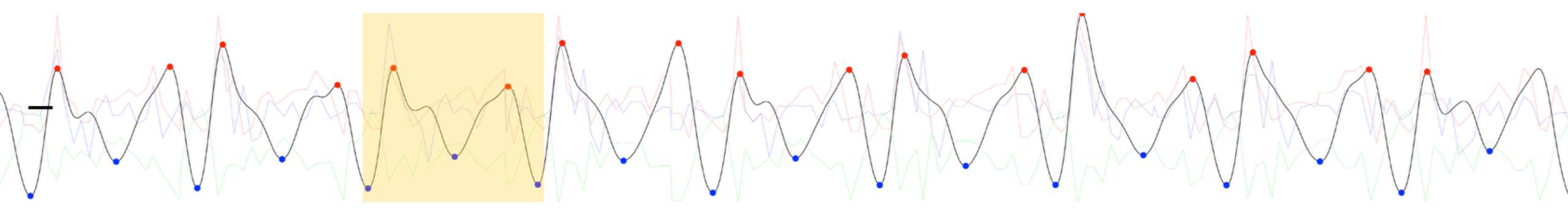
## Quotidian Rhythms Political Frictions

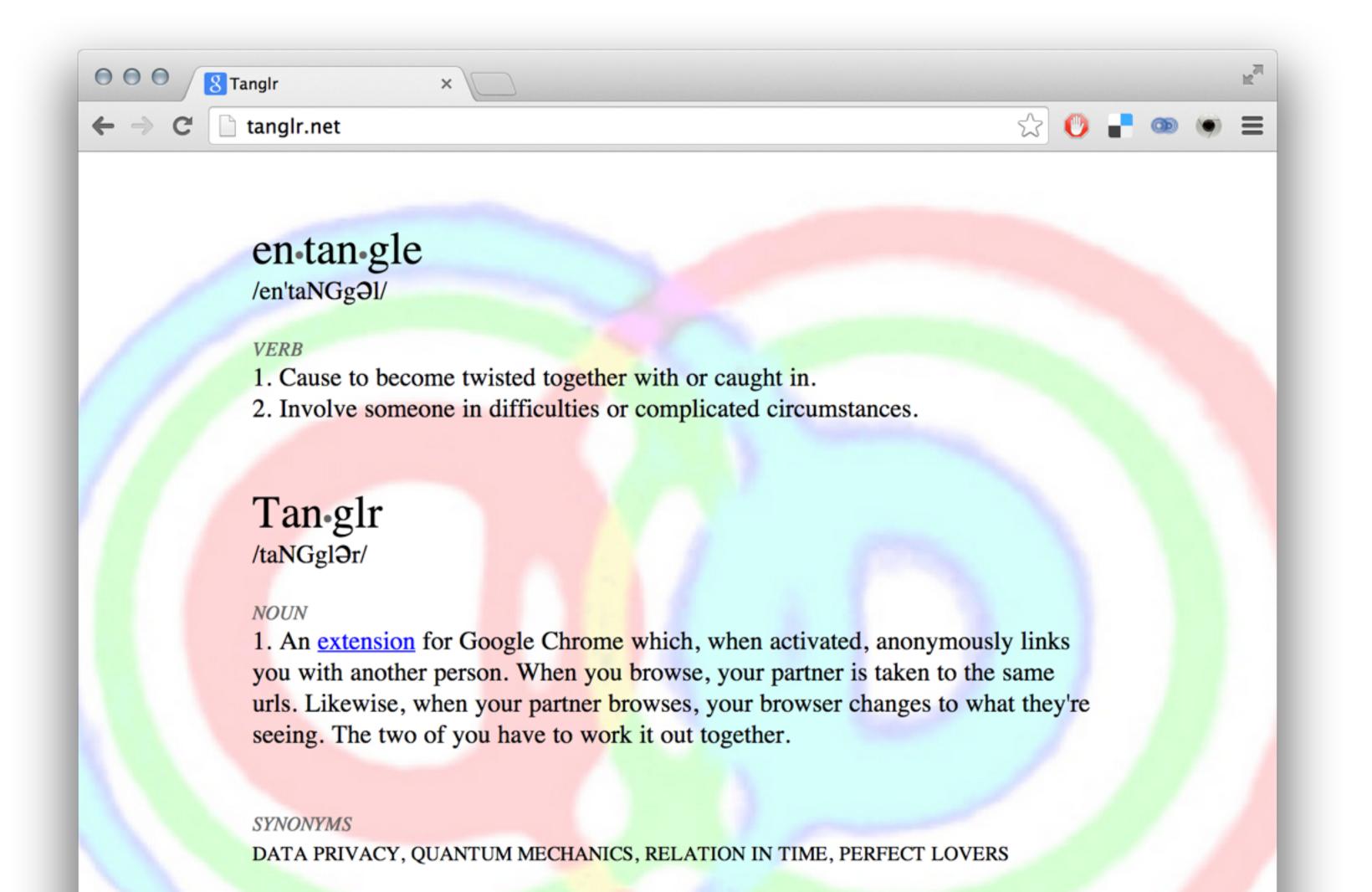
Brian House http://brianhouse.net @h0use



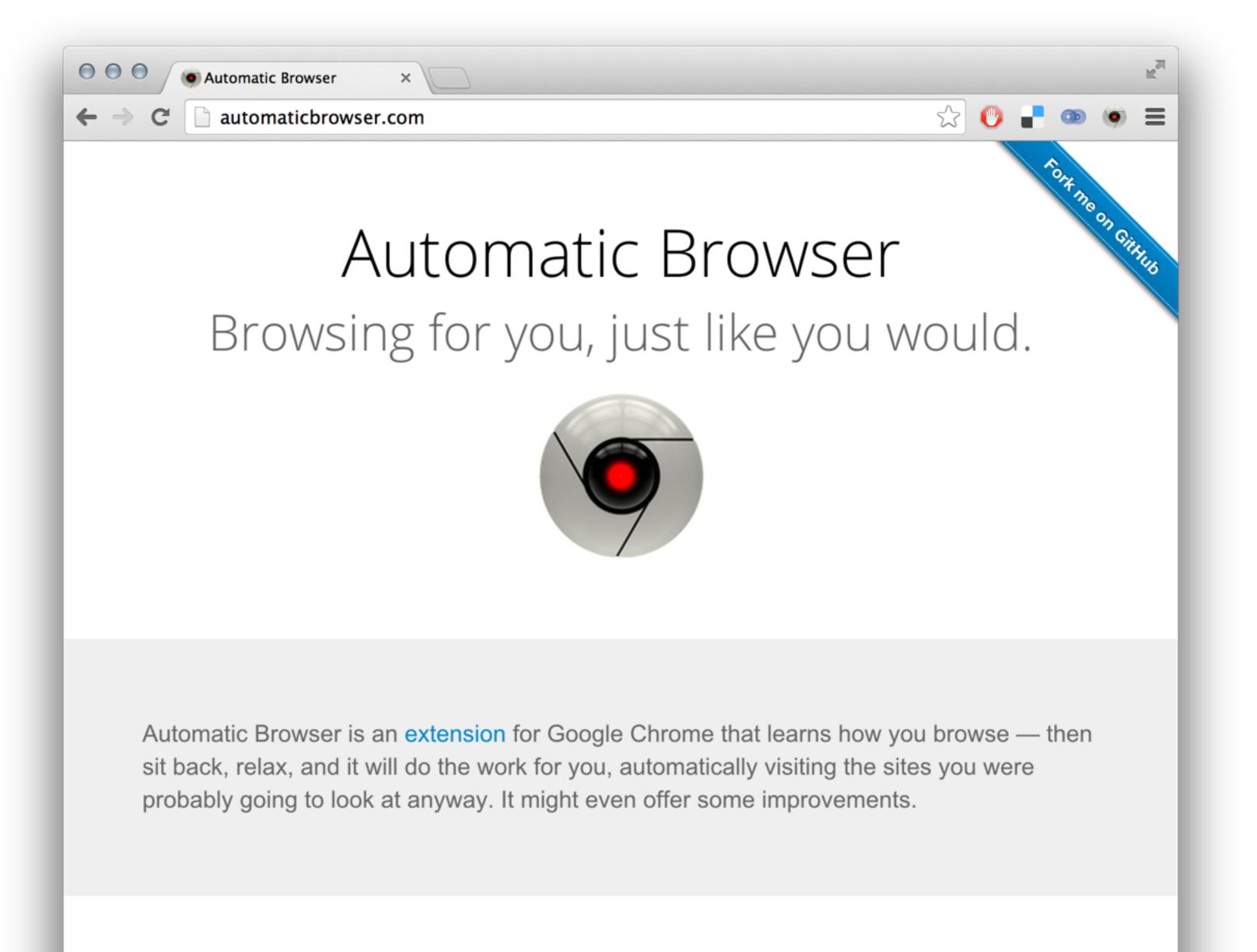








brianhouse.net



```
[house@granu]:~/Archive/2011-2012 brooklyn/joyride$ cat thief_directions.txt
Head northwest on W 5th St toward S Spring St
Turn left onto S Flower St
Take the 1st left onto W 6th St
Head southeast on W 6th St toward S Hope St
Take the 2nd right onto S Grand Ave
Head southwest on S Grand Ave toward W 7th St
Take the 1st left onto W 7th St
Take the 1st left onto S Olive St
Turn left onto W 5th St
Take the 2nd left onto S Flower St
Head southwest on S Flower St toward W 6th St
Turn right onto W 8th St
Merge onto CA-110 N via the ramp to Pasadena
Take exit 24A to merge onto US-101 N toward Hollywood
Take exit 24 for Tampa Ave
Turn right onto Tampa Ave
Turn right onto Kittridge St
Head east on Kittridge St toward Wystone Ave
Take the 2nd right onto Wilbur Ave
Turn right onto Ventura Blvd
Turn right to merge onto US-101 S
Take exit 19A for I-405 S/San Diego Fwy
Merge onto I-405 S
Take exit 53 toward I-10 E/Santa Monica
Merge onto I-10 W
Take exit 1B toward Lincoln Blvd/CA-1 S
Merge onto Olympic Blvd
Turn left onto Lincoln Blvd
Turn right onto Sunset Ave
Turn left
Turn right
Head northeast
Turn left toward Sunset Ave
Turn right onto Sunset Ave
Turn left onto Lincoln Blvd
Turn right onto Olympic Blvd
Merge onto I-10 E via the ramp to Los Angeles
Take exit 3A to merge onto I-405 N toward Sacramento
Take exit 63B to merge onto US-101 N toward Ventura
Take exit 24 for Tampa Ave
Turn right onto Tampa Ave
```



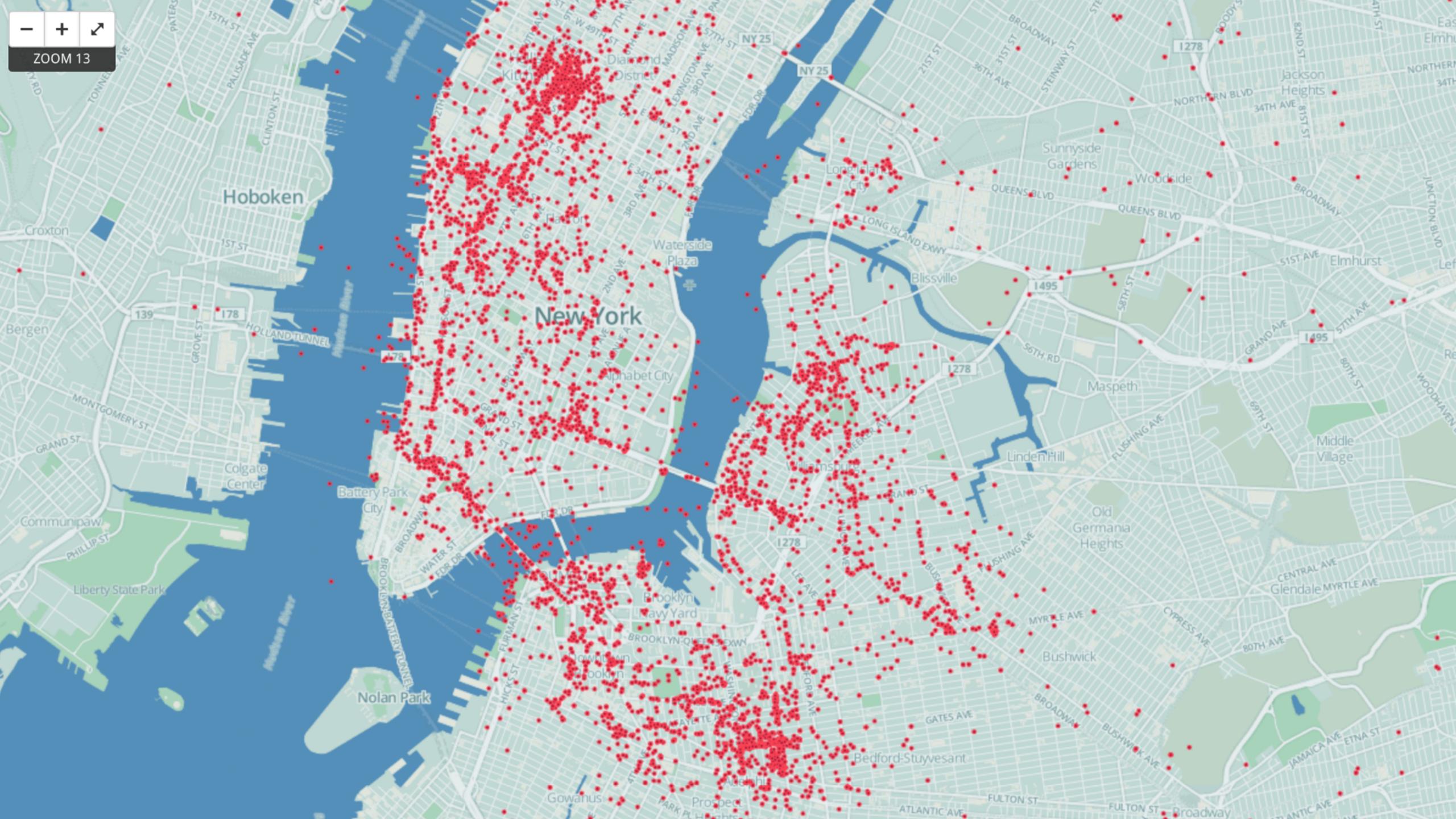






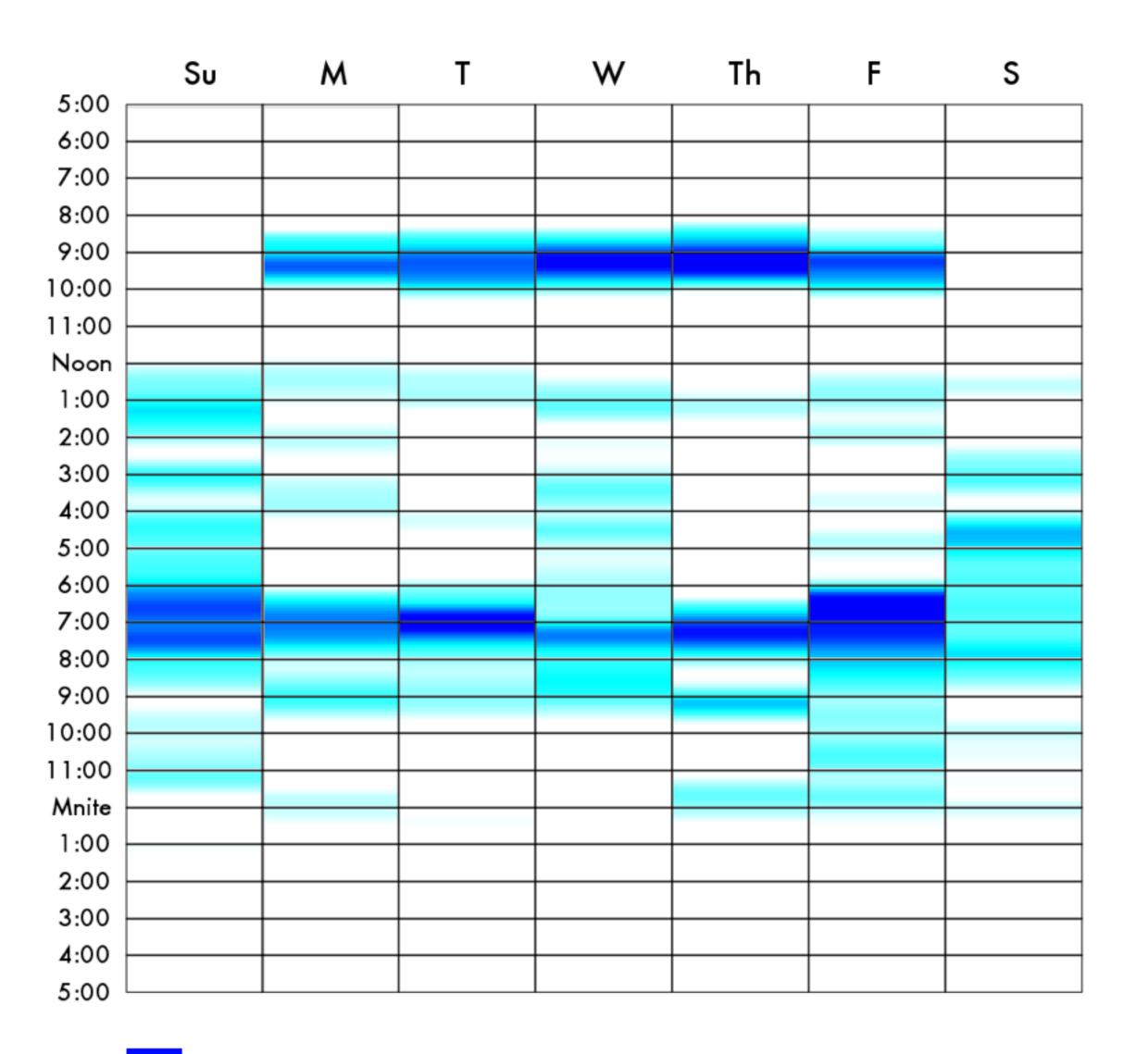
LAGISHALLMAN GOOD CAN WAN VACAS MUCCOS DUCAMERQUELOS ISSANDAS CONTROL OF CONT Family in justice in resultings with Court SQ Jac - sul TWO8\_H4dTsgWL0ZamcVQXLEGZ0V0FsejA0Vbr9pvoMZZEcTjrIhevfkL0\_gthuccuming ADM SAMAN MAGE TO GATE VINCE SAME AND WIN F256QuXadh5G1zj-nbrfF0oq8aCmhbuhNnuLFDHHR4coBH-WQHFejoday1Dab7UzeLtIzJmQyQuage Samay AREA VIEW LYCHYLLE ZYLN; Elluybinthy ZAce fd DbnJ Yn-wyn PZgX\_24MBu 706ESCmQt GZI2Jj JFG\_Mhua6U-PyUmsC4Ke45X517mbmi 0.3gz87xn972ZdLluybinthy ZAce fd DbnJ Yn-wyn PZgX\_24MBu 706ESCmQt GZI2Jj JFG\_Mhua6U-PyUmsC4Ke45X517mbmi 0.3gz87xn972ZdLluybinthy ZAce fd DbnJ Yn-wyn PZgX\_24MBu 706ESCmQt GZI2Jj JFG\_Mhua6U-PyUmsC4Ke45X517mbmi 0.3gz87xn972ZdLluybinthy ZAce fd DbnJ Yn-wyn PZgX\_24MBu 706ESCmQt GZI2Jj JFG\_Mhua6U-PyUmsC4Ke45X517mbmi 0.3gz87xn972ZdLluybinthy ZAce fd DbnJ Yn-wyn PZgX\_24MBu 706ESCmQt GZI2Jj JFG\_Mhua6U-PyUmsC4Ke45X517mbmi 0.3gz87xn972ZdLluybinthy ZAce fd DbnJ Yn-wyn PZgX\_24MBu 706ESCmQt GZI2Jj JFG\_NygYZA-RqlbhOmi 0.3gz87xn972ZdLluybinthy ZAce fd DbnJ Yn-wyn PZgX\_24MBu 706ESCmQt GZI2Jj JFG\_NygYZA-RqlbhOmi 0.3gz87xn972ZdLluybinthy ZAce fd DbnJ Yn-wyn PZgX\_24MBu 706ESCmQt GZI2Jj JFG\_NygYZA-RqlbhOmi 0.3gz87xn972ZdLluybinthy ZAce fd DbnJ Yn-wyn PZgX\_24MBu 706ESCmQt GZI2Jj JFG\_NygYZA-RqlbhOmi 0.3gz87xn972ZdLluybinthy ZAce fd DbnJ Yn-wyn PZgX\_24MBu 706ESCmQt GZI2Jj JFG\_NygYZA-RqlbhOmi 0.3gz87xn972ZdLluybinthy ZAce fd DbnJ Yn-wyn PZgX\_24MBu 706ESCmQt GZI2Jj JFG\_NygYZA-RqlbhOmi 0.3gz87xn972ZdLluybinthy GZI2JJ GZIZJJ TOOQOULINIOUNINIUL FUNINA EGAFTVAKKOBUOGCODUBWSn IFES\_1z3mEYGNhBYYrV4q1wj2exfxTqt4tYVtwOzZBaHEEZ1YviKuOTK2hW, f88n2lusus AND THE RESERVENCE OF THE PROPERTY OF THE PROP TABLE VICTOR OF THE ACMIT AND THE RESIDENCE OF THE STREET The state of the s The state of the s AND THE RESIDENCE OF THE PROPERTY OF THE PROPE TO EXECUTE TO THE PROPERTY OF TARGET SEED IN THE COMMISSION OF STREET OF STR Was and Manager an I LUNG9 eYLODGOB XWLtGSKX-e8avJu9eJAFneddtZ4gbØrsHA4EKHnlpotgom-Ballendobergem-Ballendobergem-Ballendobergem-B Ballendobergem-





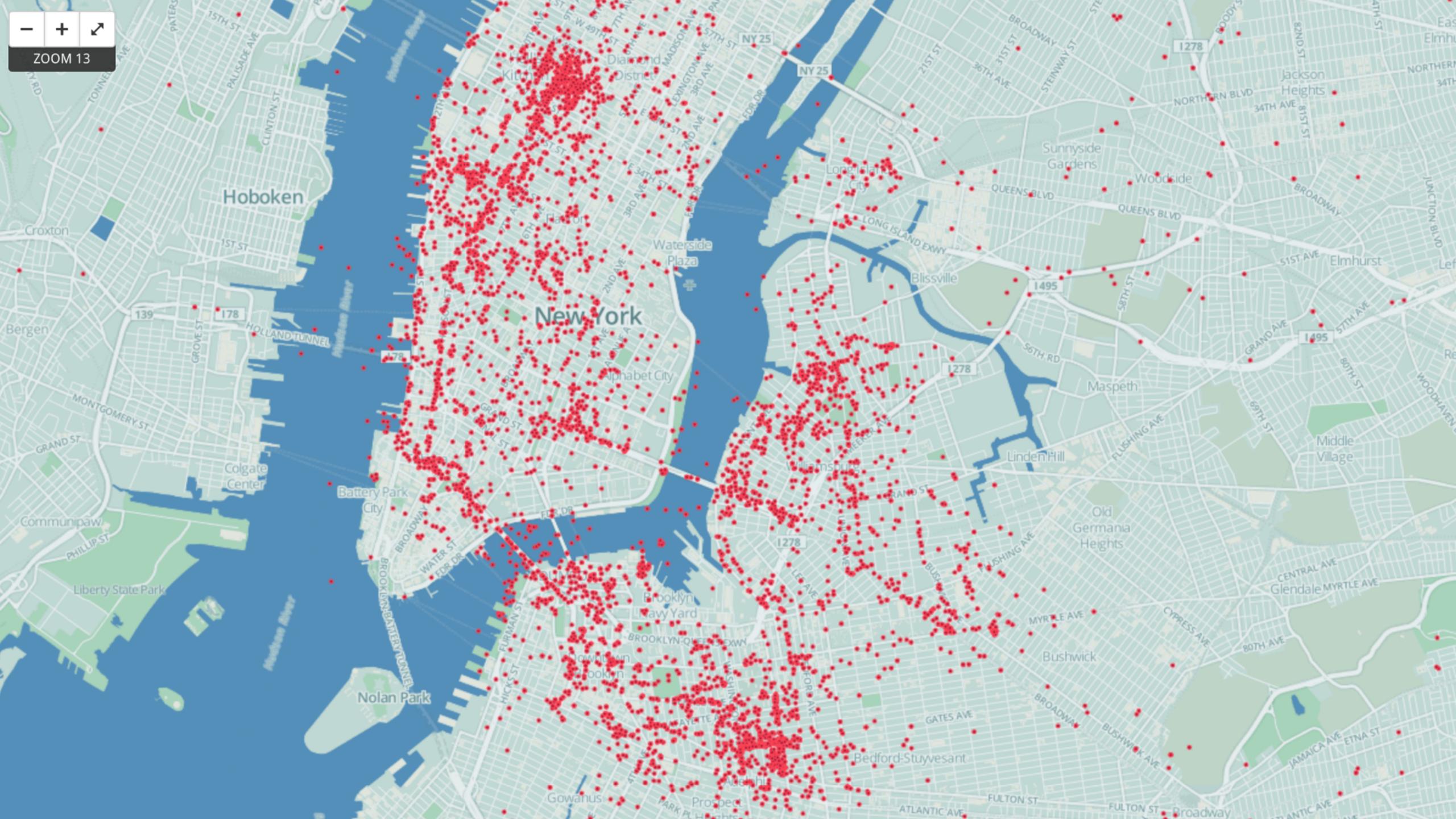
However useful this "flattening out" may be, it transforms the *temporal* articulation of places into a *spatial* sequence of points. A graph takes the place of an operation. A reversible sign is substituted for a practice indissociable from particular moments and "opportunities" ... it is thus a mark *in place of* acts, a relic in place of performances: it is only their remainder, the sign of their erasure.

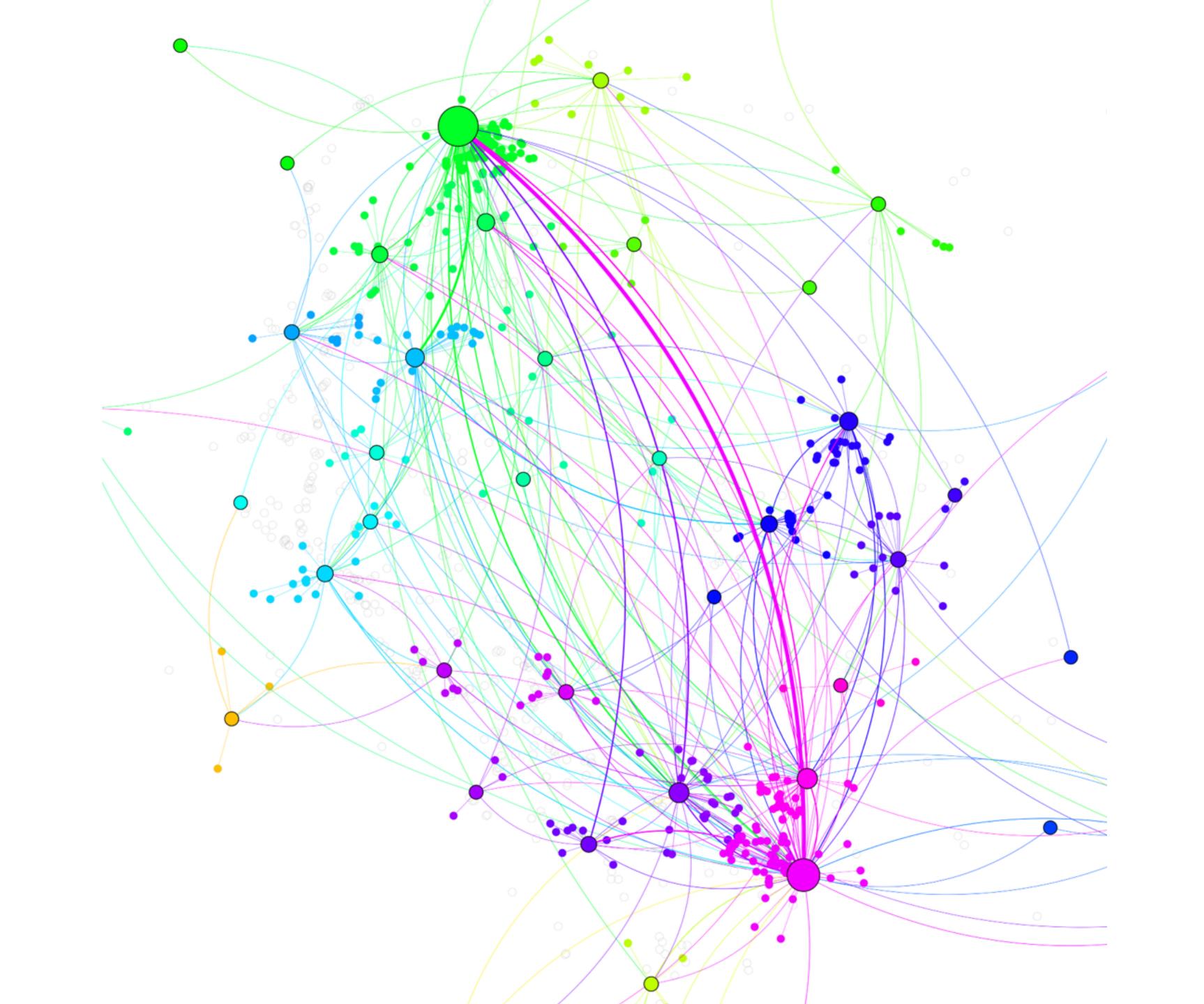
-Michel de Certeau, The Practice of Everyday Life

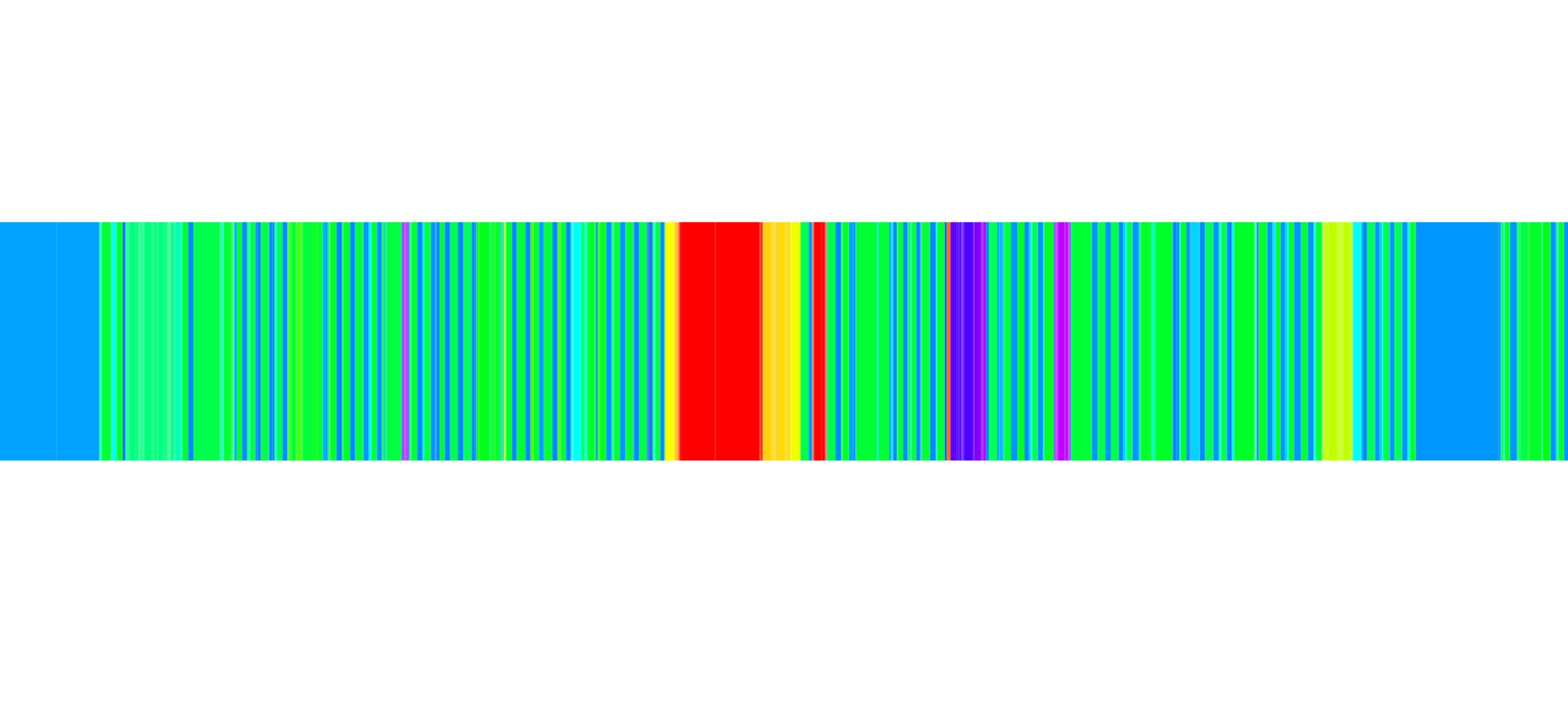


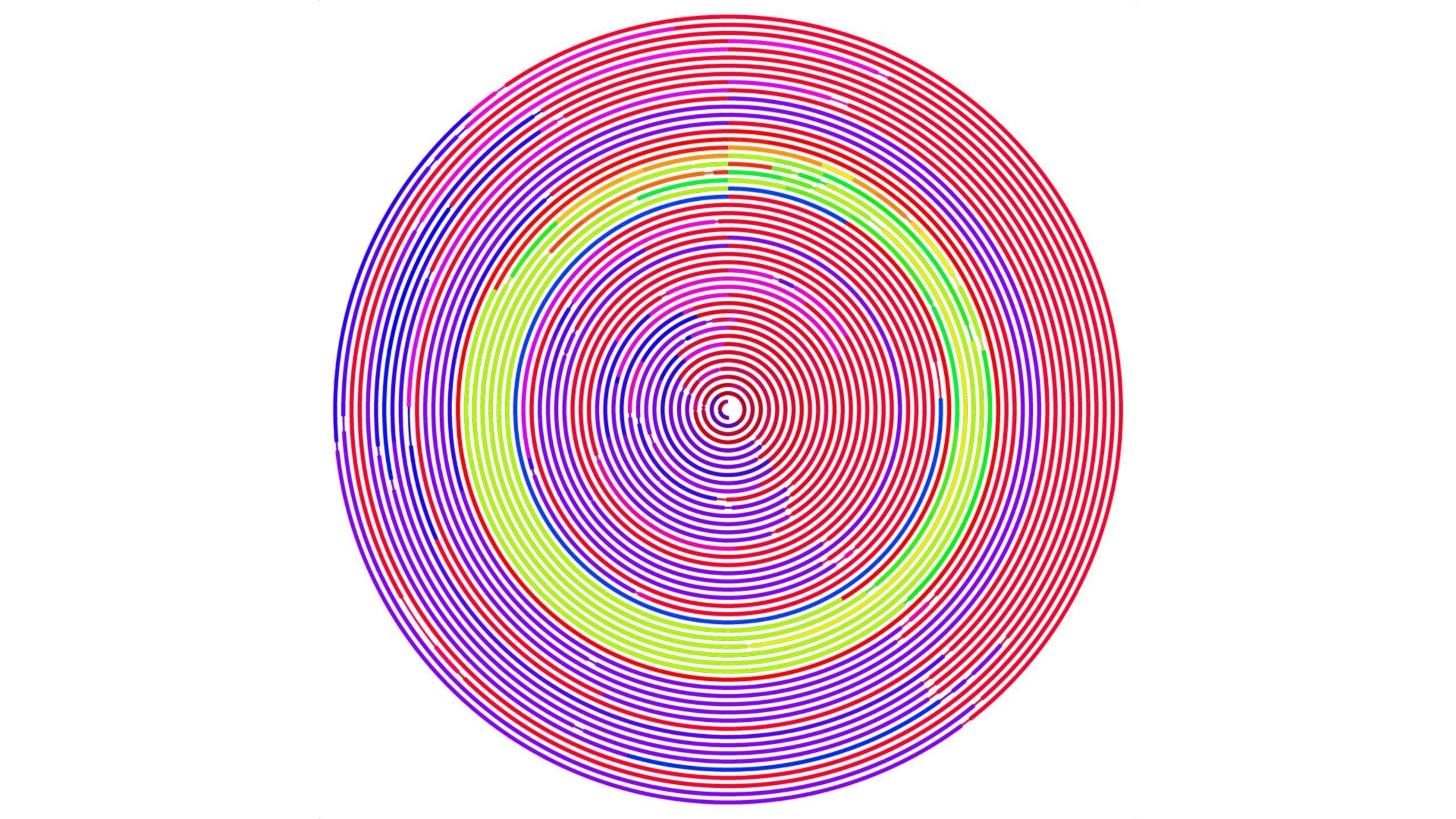








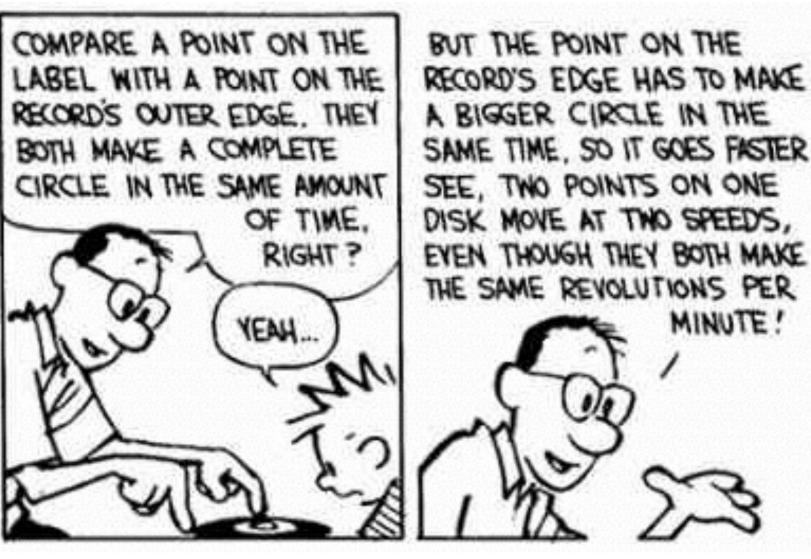


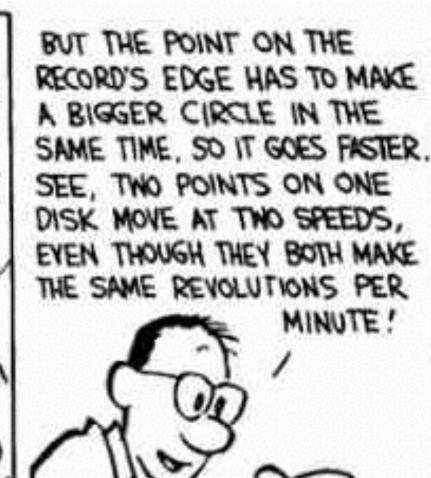




## 1 day of lived time → 1 rotation 1 rotation at $33\frac{1}{3}$ rpm = 1.8 seconds 365 rotations ~= 11 minutes











## city → musical key place → musical interval

More frequently visited places are mapped to more consonant intervals – deviation produces outer harmonies

grid: 2-hrs / 0.15s

voice 1: diurnal pulse

voice 2: geo-driven melody

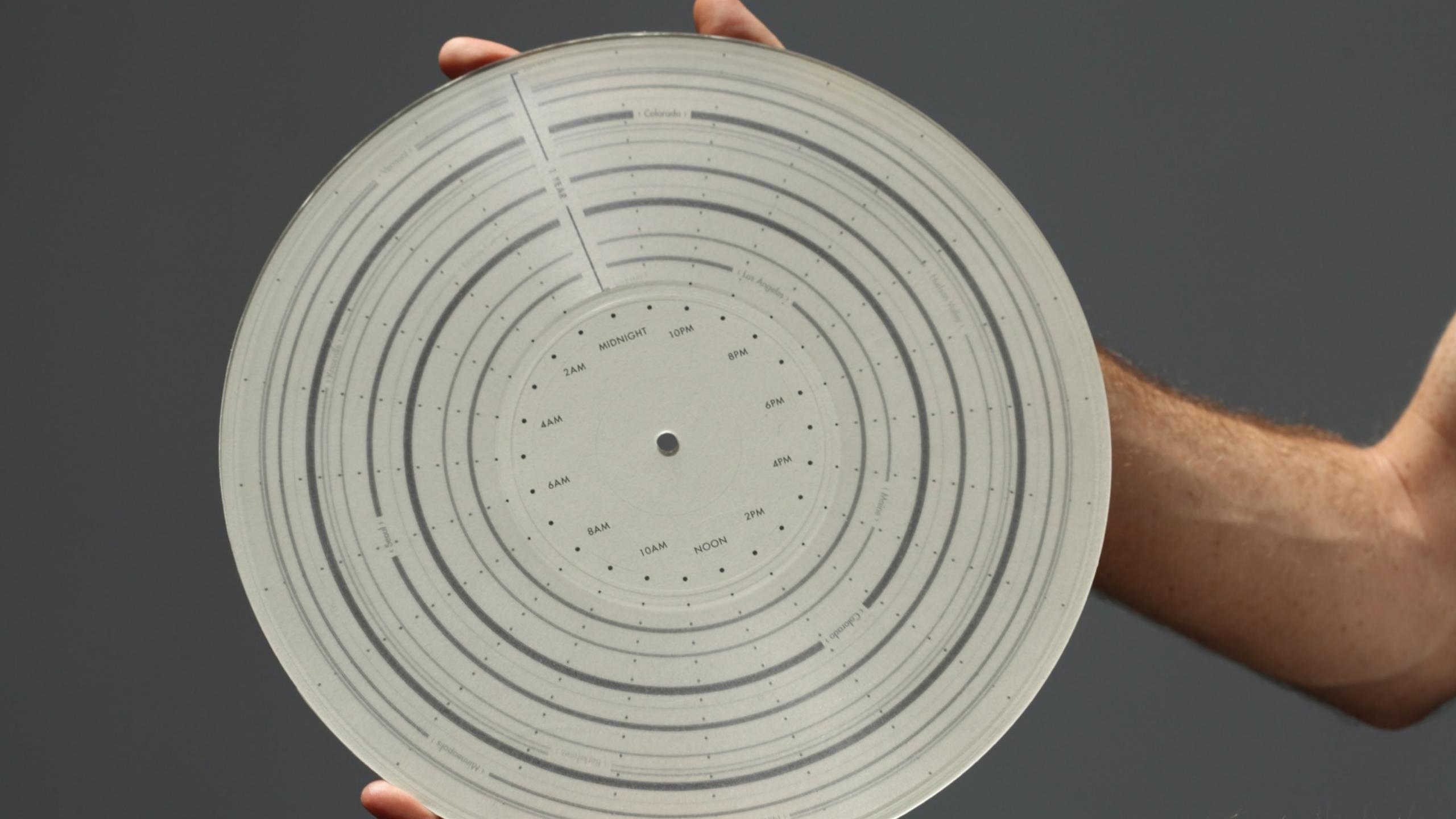
```
1 #!/usr/bin/env python3
 3 import sys, os, json, time, random, datetime, math
 4 from quotidio import model
 5 from quotidio.housepy import log, config, util, osc
 6 from braid.notation import *
                 [C, G, D, F3, G2, E, A3, F, B3, A, E3, B, D3, C5, C2]
 8 R00TS =
9 ROOT_SCALES = [MAJ, MYX, DOR, LYD, MYX, PRG, AOL, LYD, LOC, AOL, PRG, LOC, DOR, MAJ, MAJ]
10 HARMONY = [3, -6, 5, 5, -4, -4, 7, 7, 7, 7, -2, -2, -2, -2]
11
12 # get locations and how long in each
13 cities = {}
14 locations = []
15 for i, d in enumerate(data):
        city, place = int(d['city']), int(d['place'])
16
17
        if city == -1 or place == -1:
18
           continue
19
        start_time = d['pos'] * duration
        if i == len(data) - 1:
20
21
           stop_time = start_time + 1.0
22
        else:
23
           stop_time = data[i+1]['pos'] * duration
24
        location_duration = stop_time - start_time
25
        if city not in cities:
26
           cities[city] = {}
27
        if place not in cities[city]:
28
           cities[city][place] = 0.0
29
        cities[city][place] += location_duration
30
        locations.append((start_time, location_duration, city, place, d['t']))
31
32
33 # find order indexes for cities and places by total duration
34 for city, places in list(cities.items()):
35
       values = list(places.values())
36
        cities[city] = sum(values), places
37
        values.sort()
38
       values.reverse()
39
        for p, value in list(places.items()):
           places[p] = values.index(value)
40
41 values = list(cities.values())
42 values.sort(key=lambda x: x[0])
43 values.reverse()
44 max_places = 0
45 for c, value in list(cities.items()):
        cities[c] = values.index(value), value[1]
        if len(value[1]) > max_places:
47
           max_places = len(value[1])
48
49 log.debug("CITIES")
50 cs = list(cities.items())
51 cs.sort(key=lambda x: x[1])
52 for city, places in cs:
        print(("%s: %s %s" % (places[0], city, places[1])))
54 log.info("TOTAL_CITIES %s" % len(cities))
55 log.info("MAX_PLACES %s" % max_places)
57
```

```
58 # bucket all the locations into units (we want a value in every slot)
 59 units = [None] * (total_units + 10)
 60 for l, location in enumerate(locations):
        index = int(location[0] / unit_duration)
 61
 62
        # put in next available slot
         while index < len(units) and units[index] is not None:</pre>
 63
 64
             index += 1
         units[index] = location
 65
 66
         # backfill any holes with the last value
 67
         index -= 1
 68
         while l > 0 and index >= 0 and units[index] is None:
 69
             units[index] = locations[l-1]
 70
             index -= 1
 71
 72
 73 # make some notes
 74 notes = []
 75 previous_location = None
 76 for unit, location in enumerate(units):
 77
        if location is None:
 78
             continue
 79
        t = unit * unit_duration
        start_time, note_duration, city, place, real_time = location
 80
 81
         root = ROOTS[cities[city][0] % len(ROOTS)]
 82
         root_scale = ROOT_SCALES[cities[city][0] % len(ROOT_SCALES)]
 83
 84
         ##### TIMEKEEPER
 85
         velocity = 1.0 - 0.05
 86
         velocity += (random.random() * 0.1) - 0.05
 87
         # dist = abs((5.5 - ((unit - 5.5) \% 12)) / 5.5)
 88
         dist = dists[unit % 12]
 89
        velocity -= (1.0 - dist) * 0.35
 90
         velocity = int(velocity * 127)
 91
 92
         display_time = str(datetime.datetime.utcfromtimestamp(real_time))
 93
         notes.append((t, [VOICE_2, root, velocity, (unit % 12) * 2, display_time, city, place]))
 94
 95
 96
         ##### MELODY
         if location is not previous_location or random.random() > 0.8:
 97
 98
 99
             index = cities[city][1][place]
100
             add_octave = False
            if index >= len(HARMONY):
101
102
                index = index % len(HARMONY)
103
                 add_octave = True
104
            harmony = HARMONY[index]
105
            oct_shift = -12 if harmony < 0 else 0
106
            if add_octave:
107
                 if oct_shift < 0:
108
                     oct_shift -= 12
109
                else:
                    oct_shift += 12
110
            pitch = root + root_scale[abs(harmony)] + oct_shift
111
112
            velocity = 1.0 - 0.25
113
            velocity += (random.random() * 0.5) - 0.25
114
115
            velocity = int(velocity * 127)
116
117
             notes.append((t, [VOICE_1, pitch, velocity, (unit % 12) * 2, display_time, city, place]))
118
119
         previous_location = location
```

57

120













What I'm interested in is a compositional process and a sounding music that are one and the same thing.

-Steve Reich, Music as a Gradual Process

Musical rhythm ... has an ethical function. In its relation to the body, to time, to the work, it illustrates real (everyday) life.

-Henri Lefebvre, Rhythmanalysis

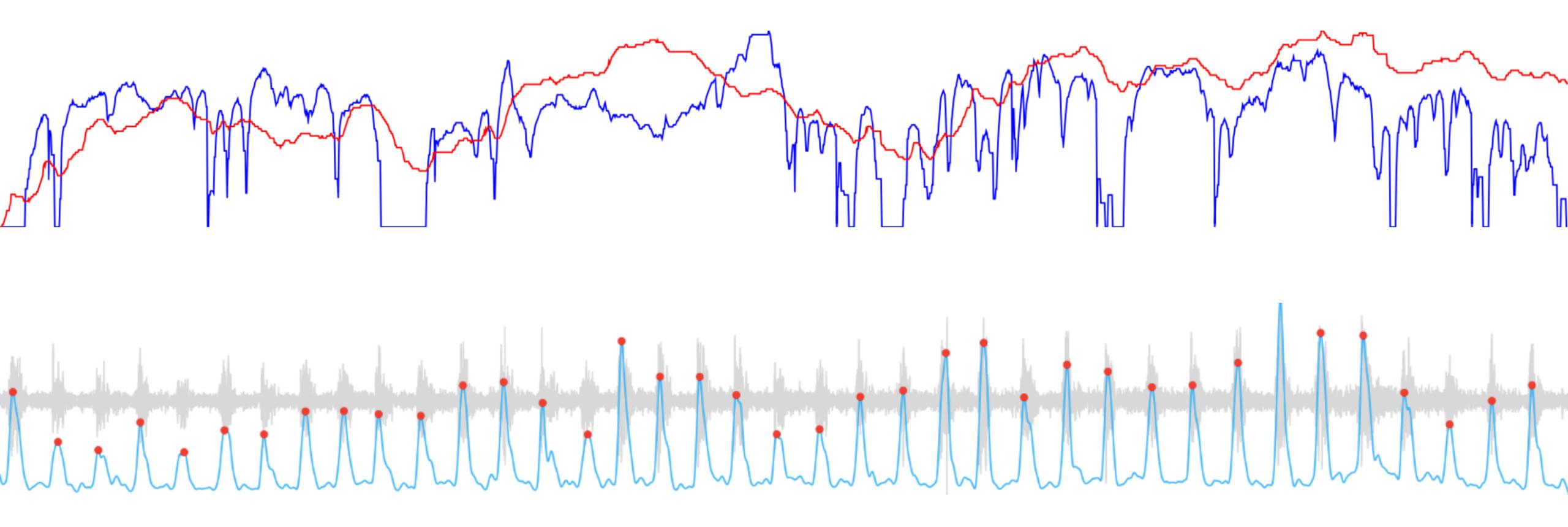
Through a certain use of time the citizen resists the state ... civil, therefore social, time seeks to and succeeds in withdrawing itself from linear, unirhythmic, measuring/measured state time.

-Henri Lefebvre, Rhythmanalysis

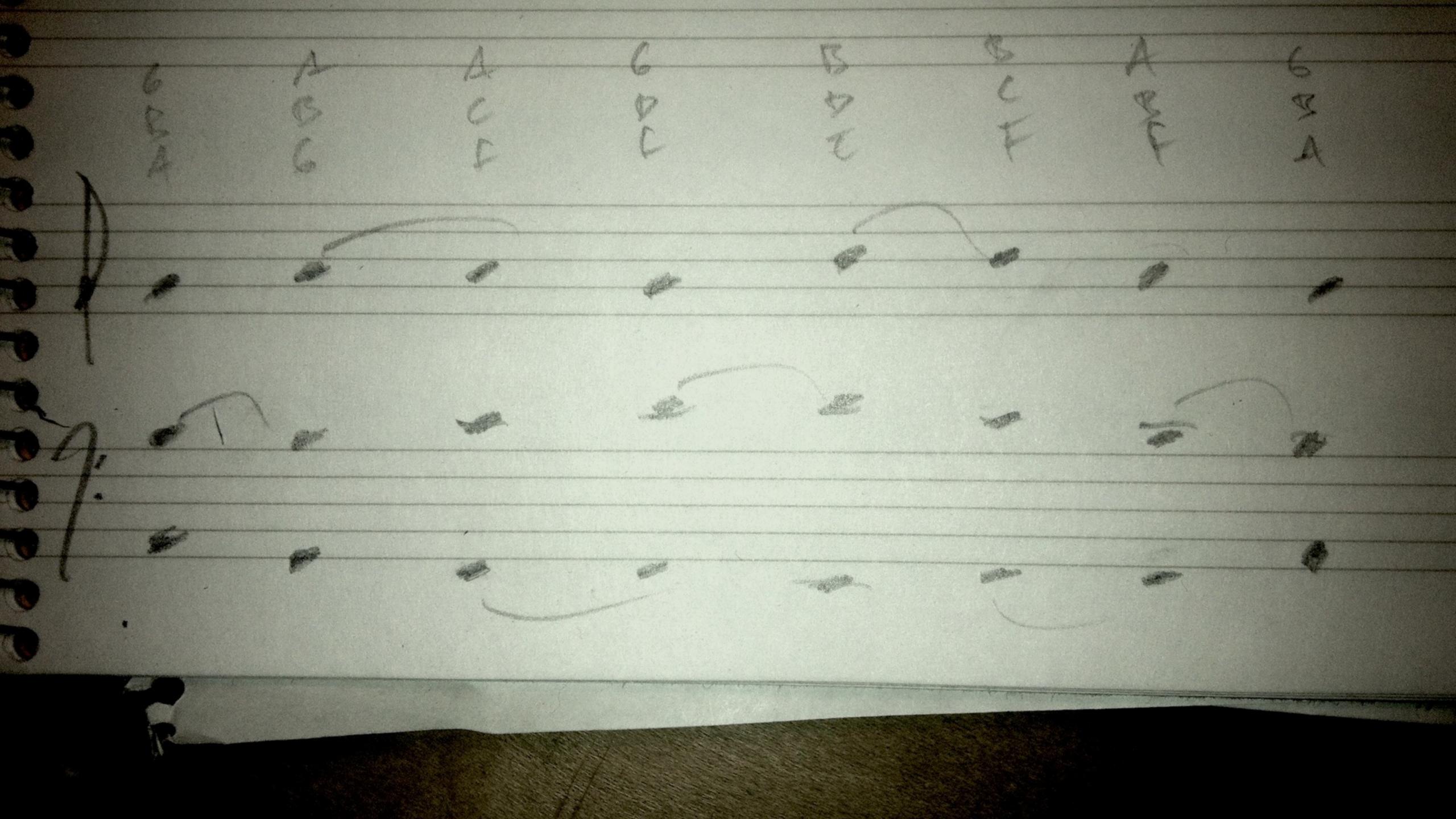








```
heartrate → bass / pizzicato pedaling → cello / arco breathing → viola / scraping
```













Buffer Address (Hex)	Relative Time (calc.) (Seconds)	Restraint Deployment Signal	Speed, Vehicle Indicated	Accelerator Pedal % Full	Engine Throttle % Full	Brake Switch	Brake SC De-ac	ABS	Transmission Neutral
		(Received / Not Received)	(MPH [km/h])	(%)	(%)	(On / Off)	(On / Off)	(Active / Inactive)	(Neutral / Not Neutral)
EA000630	-7.6	Not Received	89 [143]	96	99	OFF	OFF	Not Active	Not Neutral
EA000640	-7.4	Not Received	89 [143]	98	98.5	OFF	OFF		Not Neutral
EA000650	-7.2	Not Received	89 [143]	98.5	98.5	OFF	OFF		Not Neutral
EA000660	-7.0	Not Received	90 [145]	98.5	98.5	OFF	OFF		Not Neutral
EA000670	-6.8	Not Received	89 [143]	98	98.5	OFF	OFF		Not Neutral
EA000680	-6.6	Not Received	89 [143]	95	99	OFF	OFF		Not Neutral
EA000690	-6.4	Not Received	89 [143]	97.5	98.5	OFF	OFF		Not Neutral
EA0006A0	-6.2	Not Received	90 [145]	97.5	98.5	OFF	OFF		Not Neutral
EA0006B0	-6.0	Not Received	91 [146]	100	98.5	OFF	OFF		Not Neutral
	-5.8		91 [146]	95.5	99	OFF	OFF		Not Neutral
EA0006C0		Not Received							
EA0006D0	-5.6	Not Received	91 [146]	74	98.5	OFF	OFF		Not Neutral
EA0006E0	-5.4	Not Received	93 [150]	81	98.5	OFF	OFF	Active	Not Neutral
EA0006F0	-5.2	Not Received	95 [153]	77	98.5	OFF	OFF	Active	Not Neutral
EA000700	-5.0	Not Received	97 [156]	95	98.5	OFF	OFF	Active	Not Neutral
EA000710	-4.8	Not Received	100 [161]	96.5	99	OFF	OFF	Active	Not Neutral
EA000720	-4.6	Not Received	99 [159]	99	98.5	OFF	OFF	Active	Not Neutral
EA000730	-4.4	Not Received	97 [156]	98	99	OFF	OFF	Active	Not Neutral
EA000740	-4.2	Not Received	102 [164]	100	98.5	OFF	OFF	Active	Not Neutral
EA000750	-4.0	Not Received	104 [167]	100	98.5	OFF	OFF	Active	Not Neutral
EA000760	-3.8	Not Received	108 [174]	100	98.5	OFF	OFF	Active	Not Neutral
EA000770	-3.6	Not Received	99 [159]	100	99	OFF	OFF	Active	Not Neutral
EA000780	-3.4	Not Received	92 [148]	100	98.5	ON	OFF	Active	Not Neutral
EA000790	-3.2	Not Received	56 [90]	2	47.5	OFF	OFF	Active	Neutral
EA0007A0	-3.0	Not Received	49 [79]	0	10.5	OFF	OFF	Active	Neutral
EA0007B0	-2.8	Not Received	35 [56]	Ö	11.5	OFF	OFF	Active	Neutral
EA0007C0	-2.6	Not Received	8 [13]	Ō	8	OFF	OFF	Active	Neutral
EA0007D0	-2.4	Not Received	1 [2]	0	7.5	OFF	OFF	Active	Neutral
EA0007E0	-2.2	Not Received	1 [2]	0	7.5	OFF	OFF	Active	Neutral
	-2.0				-				
EA0007F0		Not Received	0 [0]	0	6.5	OFF	OFF	Active	Neutral
EA000010	-1.8	Not Received	2 [3]	0	6	OFF	OFF		Neutral
EA000020	-1.6	Not Received	1 [2]	0	6	OFF	OFF	Not Active	
EA000030	-1.4	Not Received	2 [3]	0	5.5	OFF	OFF		Neutral
EA000040	-1.2	Not Received	1 [2]	0	5.5	OFF	OFF		Neutral
EA000050	-1.0	Not Received	0 [0]	0	5	OFF	OFF		Neutral
EA000060	-0.8	Not Received	0 [0]	0	5	OFF	OFF		Neutral
EA000070	-0.6	Not Received	1 [2]	0	5	OFF	OFF	Not Active	Neutral
EA000080	-0.4	Not Received	2 [3]	0	5	OFF	OFF	Not Active	Neutral
EA000090	-0.2	Not Received	0 [0]	0	5	OFF	OFF	Not Active	Neutral
EA0000A0	0.0	Not Received	0 [0]	0	4.5	OFF	OFF	Not Active	Neutral
EA0000B0	0.2	Received	0 [0]	0	4.5	OFF	OFF	Not Active	Neutral
EA0000C0	0.4	Received	1 [2]	0	4.5	OFF	OFF	Not Active	Neutral
EA0000D0	0.6	Received	0 [0]	0	4.5	OFF	OFF	Not Active	Neutral
EA0000E0	0.8	Received	0 [0]	Ō	4.5	OFF	OFF		Neutral
EA0000F0	1.0	Received	1 [2]	Ō	4.5	OFF	OFF		Neutral
EA000100	1.2	Received	1 [2]	0	5	OFF	OFF		Neutral
EA000110	1.4	Received	0 [0]	0	5.5	OFF	OFF		Neutral
EA000110	1.6	Received	0 [0]	0	5.5	OFF	OFF		Neutral
EA000120	1.8	Received	1 [2]	0	5.5	OFF	OFF		Neutral
	2.0		0 [0]	0	5.5	OFF	OFF		Neutral
EA000140		Received							
EA000150	2.2	Received	2 [3]	0	5.5	OFF	OFF		Neutral
EA000160	2.4	Received	1 [2]	0	5.5	OFF	OFF		Neutral
EA000170	2.6	Received	0 [0]	0	6	OFF	OFF		Neutral
EA000180	2.8	Received	0 [0]	0	6	OFF	OFF		Not Neutral
EA000190	3.0	Received	0 [0]	0	6	OFF	OFF		Not Neutral
EA0001A0	3.2	Received	0 [0]	0	6.5	OFF	OFF		Not Neutral
EA0001B0	3.4	Received	0 [0]	0	6.5	OFF	OFF		Not Neutral
EA0001C0	3.6	Received	0 [0]	0	2.5	OFF	OFF	Not Active	Not Neutral
EA0001D0	3.8	Received	0 [0]	0	9	OFF	OFF	Not Active	Not Neutral
EA0001E0	4.0	Received	0 [0]	0	9.5	OFF	OFF		Not Neutral
EA0001F0	4.2	Received	0 [0]	0	9.5	OFF	OFF		Not Neutral
EA000200	4.4	Received	0 [0]	0	9.5	OFF	OFF		Not Neutral
EA000210	4.6	Received	0 [0]	Ö	9.5	OFF	OFF		Not Neutral
EA000210	4.8	Received	0 [0]	0	9.5	OFF	OFF		Not Neutral
	- T-154	LIGOGIACA	U [U]		0.0	OII	0.1	I TOU / YOU'VE	HOLITCULIAL





PCM EDR Data (2)

Buffer Address	Relative Time (calc.)	Transmission - Reverse	Speed Control	Engine RPM	Driveline Torque Commanded	Driveline Torque Actual	Traction Control	Stability Control	Key On Timer 63.75 Max (sec
(Hex)	(Seconds)	(Reverse / Not Reverse)	(On / Off)	(RPM)	(N-m)	(N-m)	(Active / Inactive)	(Active / Inactive)	(Seconds)
EA000240	-20.2	Not Reverse	OFF	2175	168	102	Not Active	Not Active	63.75
EA000250	-20.0	Not Reverse	OFF	2174	167	102	Not Active	Not Active	63.75
EA000260	-19.8	Not Reverse	OFF	2180	168	102	Not Active	Not Active	63.75
EA000270	-19.6	Not Reverse	OFF	2185	169	103	Not Active	Not Active	
EA000280	-19.4	Not Reverse	OFF	2180	167	101	Not Active	Not Active	
EA000290	-19.2	Not Reverse	OFF	2185	168	102	Not Active	Not Active	63.75
EA0002A0	-19.0	Not Reverse	OFF	2189	169	102	Not Active	Not Active	63.75
EA0002B0	-18.8	Not Reverse	OFF	2192	175	107	Not Active	Not Active	63.75
EA0002C0	-18.6	Not Reverse	OFF	2193	175	107	Not Active	Not Active	
EA0002D0	-18.4	Not Reverse	OFF	2192	176	107	Not Active	Not Active	
EA0002E0	-18.2	Not Reverse	OFF	2200	176	107	Not Active	Not Active	
EA0002F0	-18.0	Not Reverse	OFF	2196	175	106	Not Active	Not Active	63.75
EA000300	-17.8	Not Reverse	OFF	2203	180	110	Not Active	Not Active	63.75
EA000310 EA000320	-17.6 -17.4	Not Reverse	OFF	2207 2209	182 183	111	Not Active	Not Active Not Active	
		Not Reverse				111	Not Active		
EA000330 EA000340	-17.2 -17.0	Not Reverse Not Reverse	OFF OFF	2213 2217	182 196	120	Not Active Not Active	Not Active Not Active	63.75 63.75
EA000340	-17.0	Not Reverse	OFF	2224	213	132	Not Active	Not Active	63.75
EA000350	-16.6	Not Reverse	OFF	2228	238	148	Not Active	Not Active	
EA000370	-16.4	Not Reverse	OFF	2232	235	146	Not Active	Not Active	
EA000370	-16.2	Not Reverse	OFF	2244	227	141	Not Active	Not Active	
EA000390	-16.0	Not Reverse	OFF	2248	282	178	Not Active	Not Active	63.75
EA0003A0	-15.8	Not Reverse	OFF	2318	307	193	Not Active	Not Active	63.75
EA0003B0	-15.6	Not Reverse	OFF	2712	278	177	Not Active	Not Active	63.75
EA0003C0	-15.4	Not Reverse	OFF	3079	284	206	Not Active	Not Active	63.75
EA0003D0	-15.2	Not Reverse	OFF	3296	315	250	Not Active	Not Active	63.75
EA0003E0	-15.0	Not Reverse	OFF	3400	292	248	Not Active	Not Active	63.75
EA0003F0	-14.8	Not Reverse	OFF	3393	279	240	Not Active	Not Active	63.75
EA000400	-14.6	Not Reverse	OFF	3612	297	271	Not Active	Not Active	63.75
EA000410	-14.4	Not Reverse	OFF	3633	306	282	Not Active	Not Active	63.75
EA000420	-14.2	Not Reverse	OFF	3615	308	283		Not Active	
EA000430	-14.0	Not Reverse	OFF	3318	283	234		Not Active	
EA000440	-13.8	Not Reverse	OFF	2938	369	239	Not Active	Not Active	63.75
EA000450	-13.6	Not Reverse	OFF	2989	322	211	Not Active	Not Active	63.75
EA000460	-13.4	Not Reverse	OFF	2990	322	209	Not Active	Not Active	63.75
EA000470	-13.2	Not Reverse	OFF	2990	325	210	Not Active	Not Active	63.75
EA000480	-13.0	Not Reverse	OFF	2986	322	207	Not Active	Not Active	63.75
EA000490	-12.8	Not Reverse	OFF	2936	329	207		Not Active	
EA0004A0	-12.6	Not Reverse	OFF	2827	327	204		Not Active	
EA0004B0	-12.4	Not Reverse	OFF	2746	324	202		Not Active	
EA0004C0	-12.2	Not Reverse	OFF	2642	318	199		Not Active	
EA0004D0	-12.0	Not Reverse	OFF	2494	326	205		Not Active	
EA0004E0	-11.8	Not Reverse	OFF	2424	323	203		Not Active	
EA0004F0	-11.6	Not Reverse	OFF	2435	315	198		Not Active	
EA000500	-11.4	Not Reverse	OFF	2448	316	198		Not Active	
EA000510	-11.2	Not Reverse	OFF	2454	318	200		Not Active	
EA000520	-11.0	Not Reverse	OFF	2462	319	200		Not Active	
EA000530	-10.8	Not Reverse	OFF	2470	317	199		Not Active	
EA000540	-10.6	Not Reverse	OFF	2478	318	200		Not Active	
EA000550	-10.4	Not Reverse	OFF	2491	318	199		Not Active	
EA000560	-10.2	Not Reverse	OFF	2490	318	200		Not Active	
EA000570	-10.0	Not Reverse	OFF	2499	319	200		Not Active	
EA000580 EA000590	-9.8 -9.6	Not Reverse	OFF	2517 2515	320 317	201 199		Not Active	
EA000590	-9.6 -9.4	Not Reverse Not Reverse	OFF	2515	317	199		Not Active Not Active	
EA0005A0	-9.4	Not Reverse	OFF	2536	318	199		Not Active	
EA0005C0	-9.2	Not Reverse	OFF	2551	318	199		Not Active	
EA0005C0 EA0005D0	-8.8	Not Reverse	OFF	2551	319	200		Not Active	
EA0005E0	-8.6	Not Reverse	OFF	2562	317	198		Not Active	
EA0005E0 EA0005F0	-8.4	Not Reverse	OFF	2568	316	198		Not Active	
EA0005F0	-8.2	Not Reverse	OFF	2580	316	198		Not Active	
EA000610	-8.0	Not Reverse	OFF	2584	315	197		Not Active	
EA000620	-7.8	Not Reverse	OFF	2592	317	198	Not Active		

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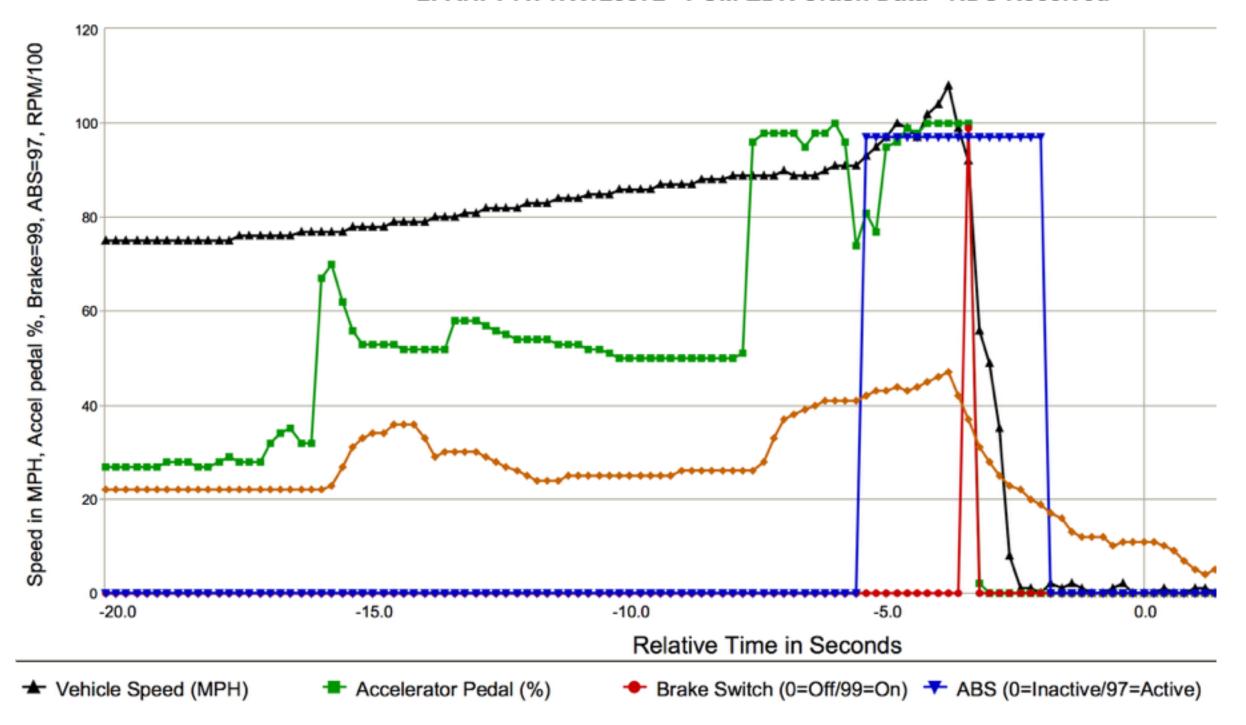
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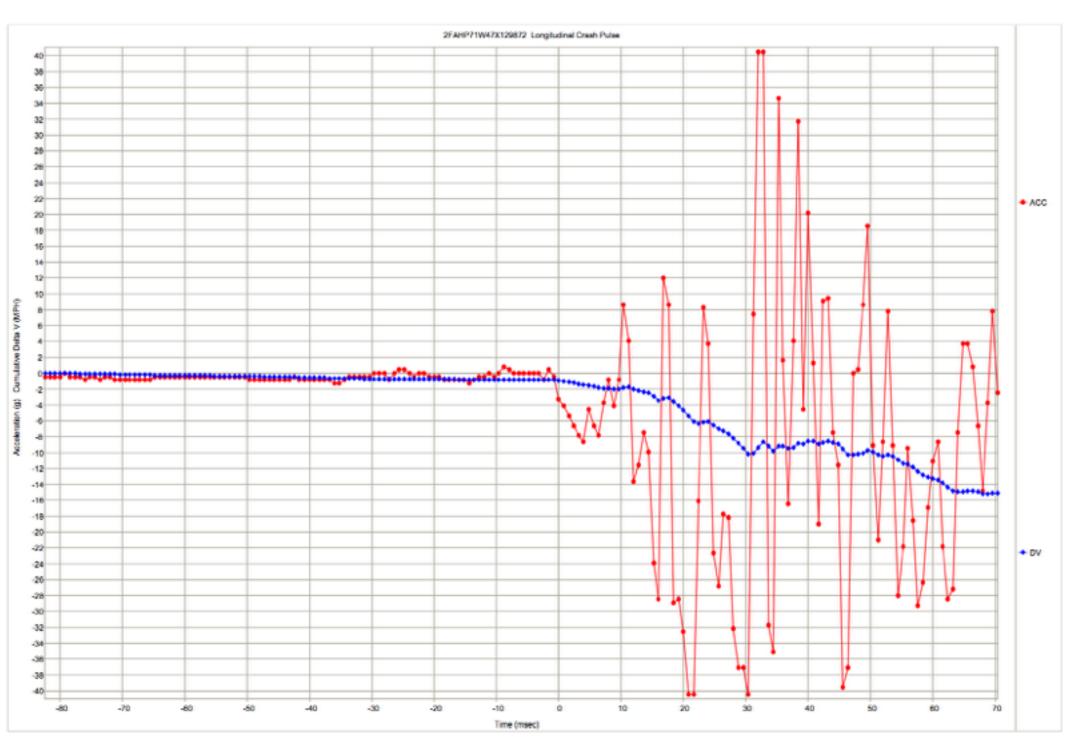
11 Print

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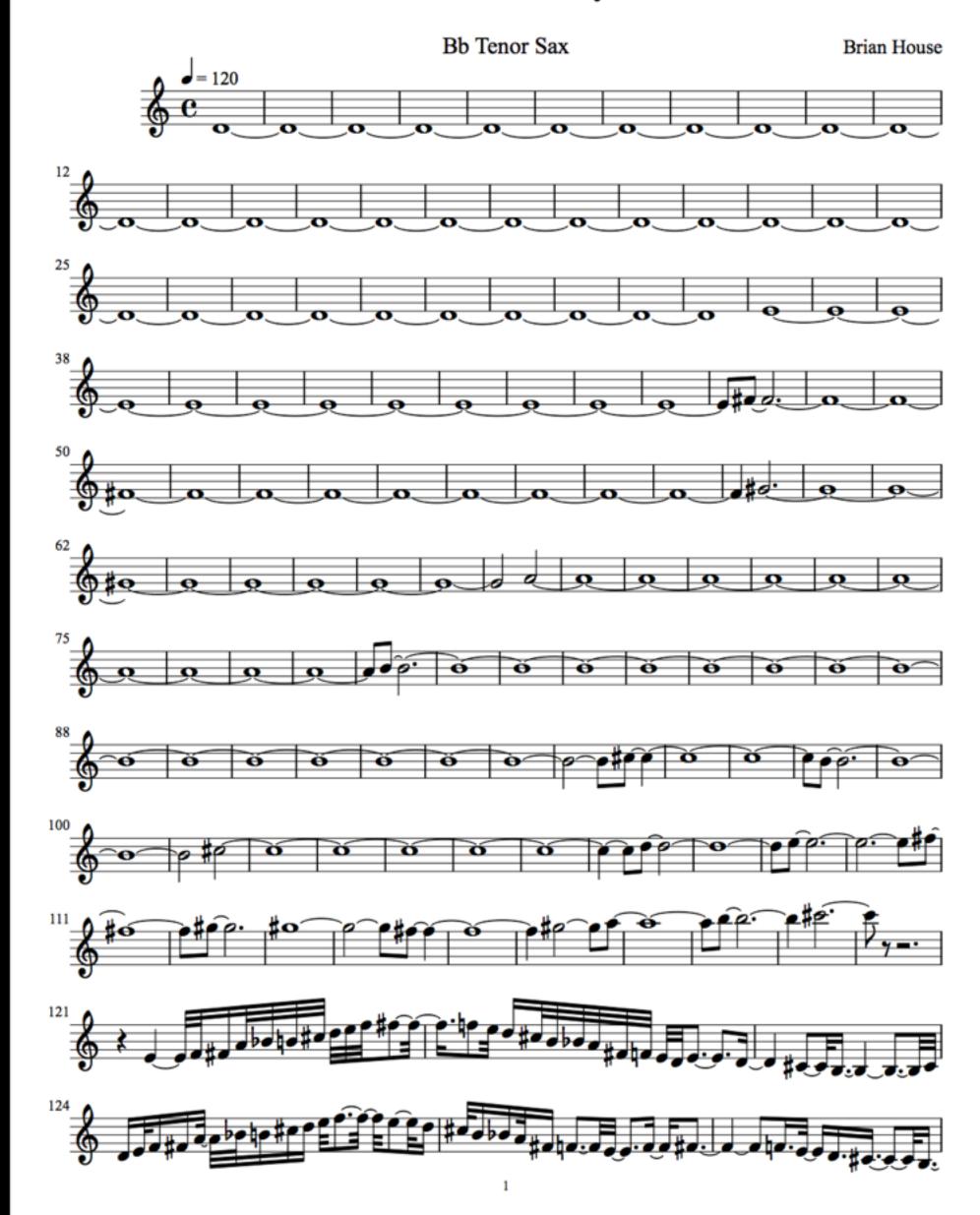
### 2FAHP71W47X129872 PCM EDR Crash Data - RDS Received





engine RPM → guitar 1, rate gas pedal % → guitar 2, rate lateral accel. → sax pitch

## You'll Just Have to Take My Word for It





The tempo is constant, but the click track must be used to stay in sync with the guitars. The click track counts in for one bar.

Sustain long notes by circular breathing. Changing notes should be played legato. The first section is just minimal movement in C-Lydian (concert).

Visually cue the guitars at the rest in bar 120, where everything changes. From this point, be as expressive as possible, even soulful in a broken, skronky, digital kind of way. Think lite jazz glitch. Extra points for body movements. This section is just runs in a kind of A-blues (concert).

The last note should be held as long as possible with a single breath, trailing off as necessary.

Play dynamics as felt.









# Instrumentation

3 Flutes (3rd doubling Piccolo) 3 Oboes (3rd doubling Cor Anglais) 2 Clarinets in A and Bb Bass Clarinet in A and Bb Alto Saxophone 2 Bassoons Double Bassoon 4 Horns in F 3 Trumpets in C 3 Trombones Tuba Timpani \*Percussion 2 Harps Celesta Strings

\*glockenspiel, tubular bells, xylophone, triangle, rattle, whip, side drum, bass drum, cymbals, tam-tam

Duration: 29 minutes

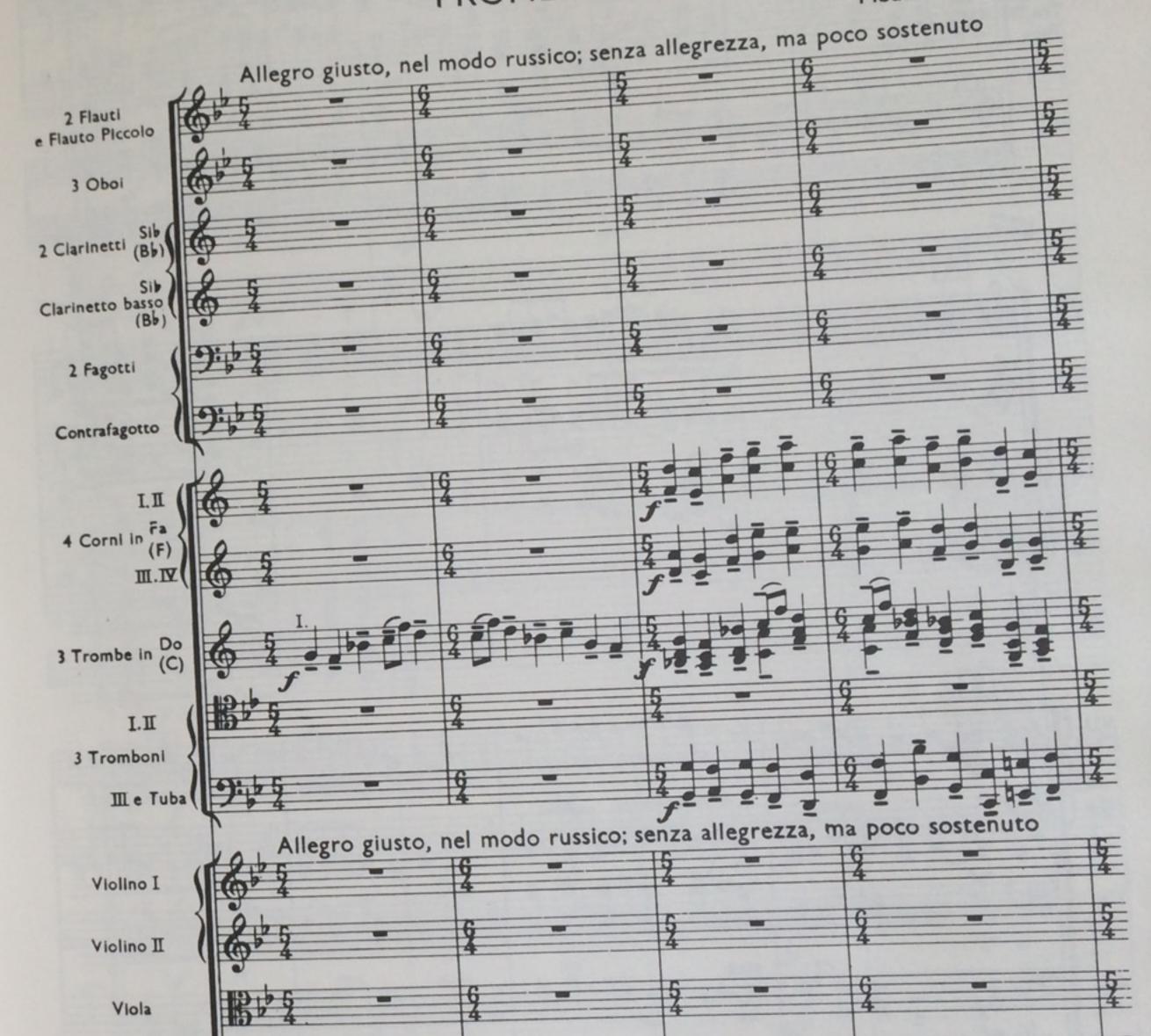
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# PICTURES AT AN EXHIBITION

Tableaux d'une Exposition • Bilder einer Ausstellung M. MOUSSORGSKY

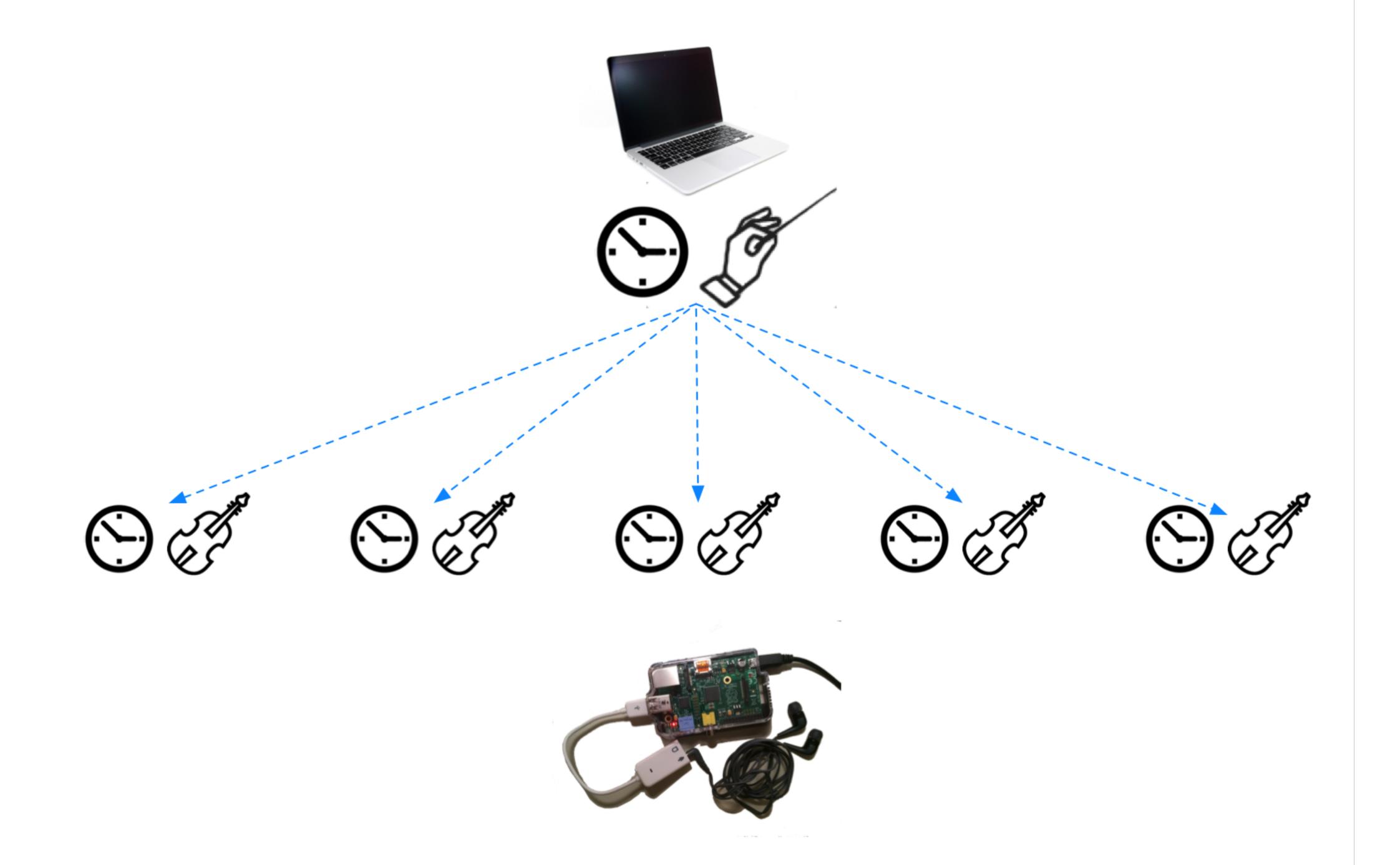
PROMENADE

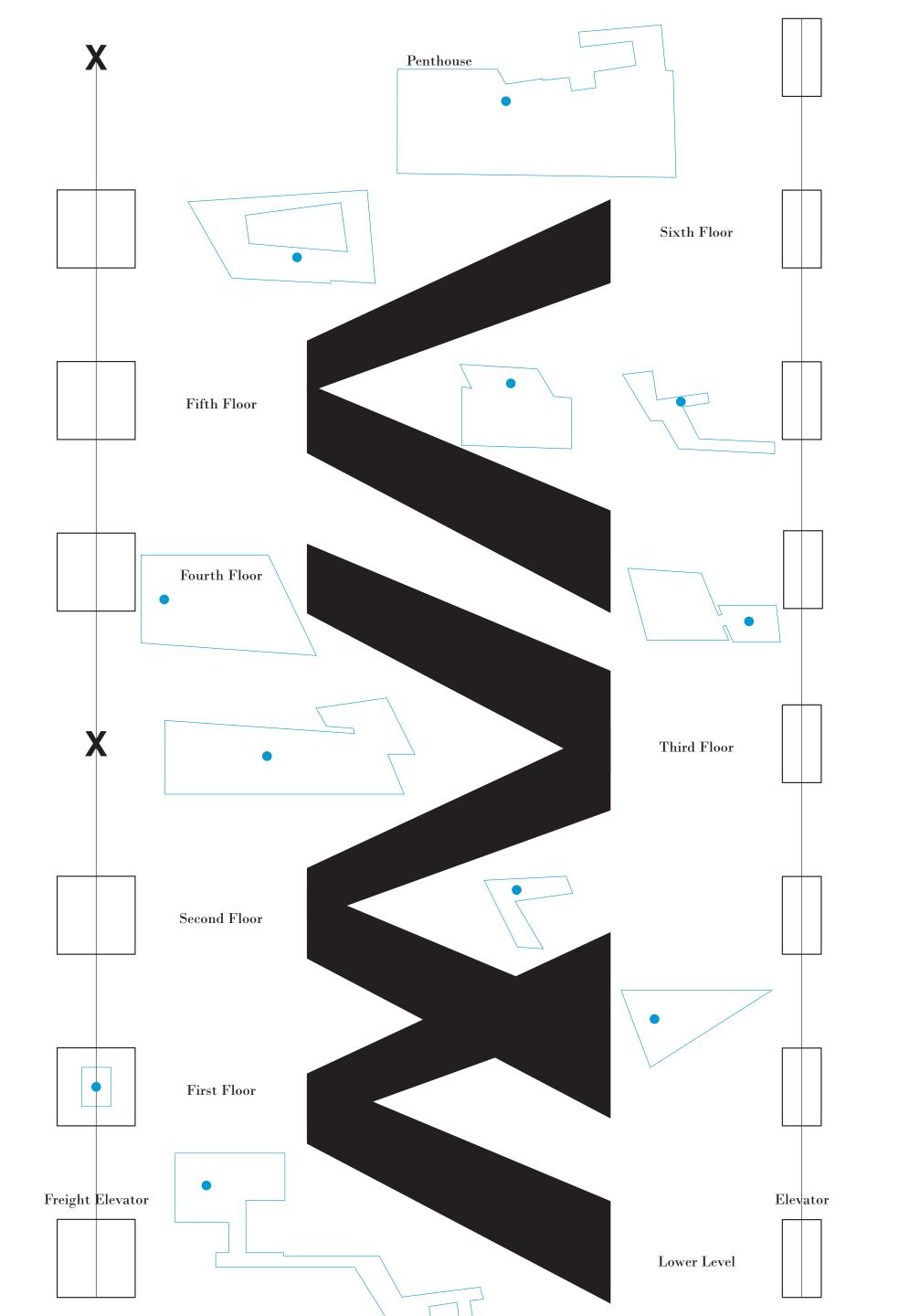
Orchestration by Maurice Ravel

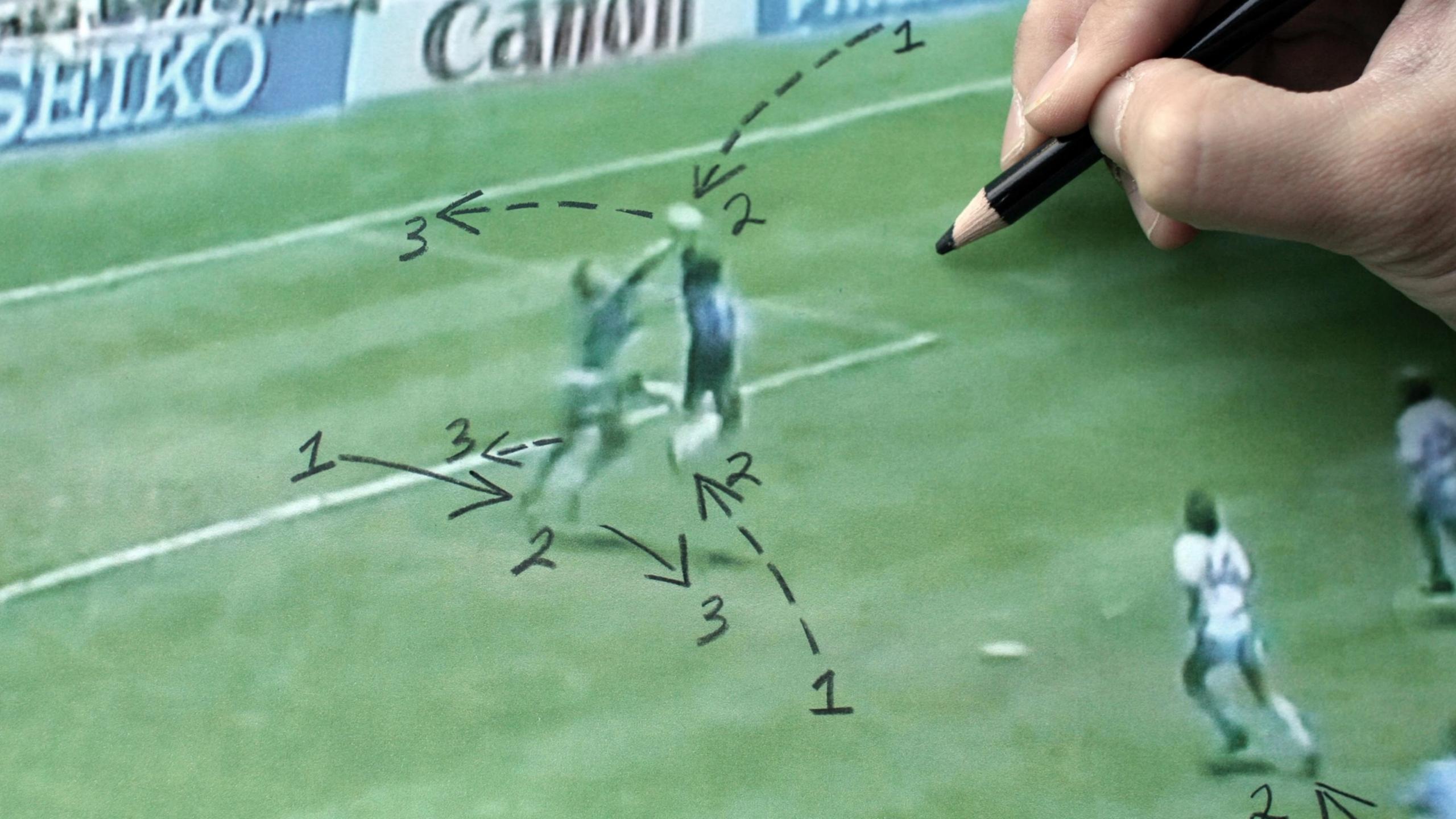


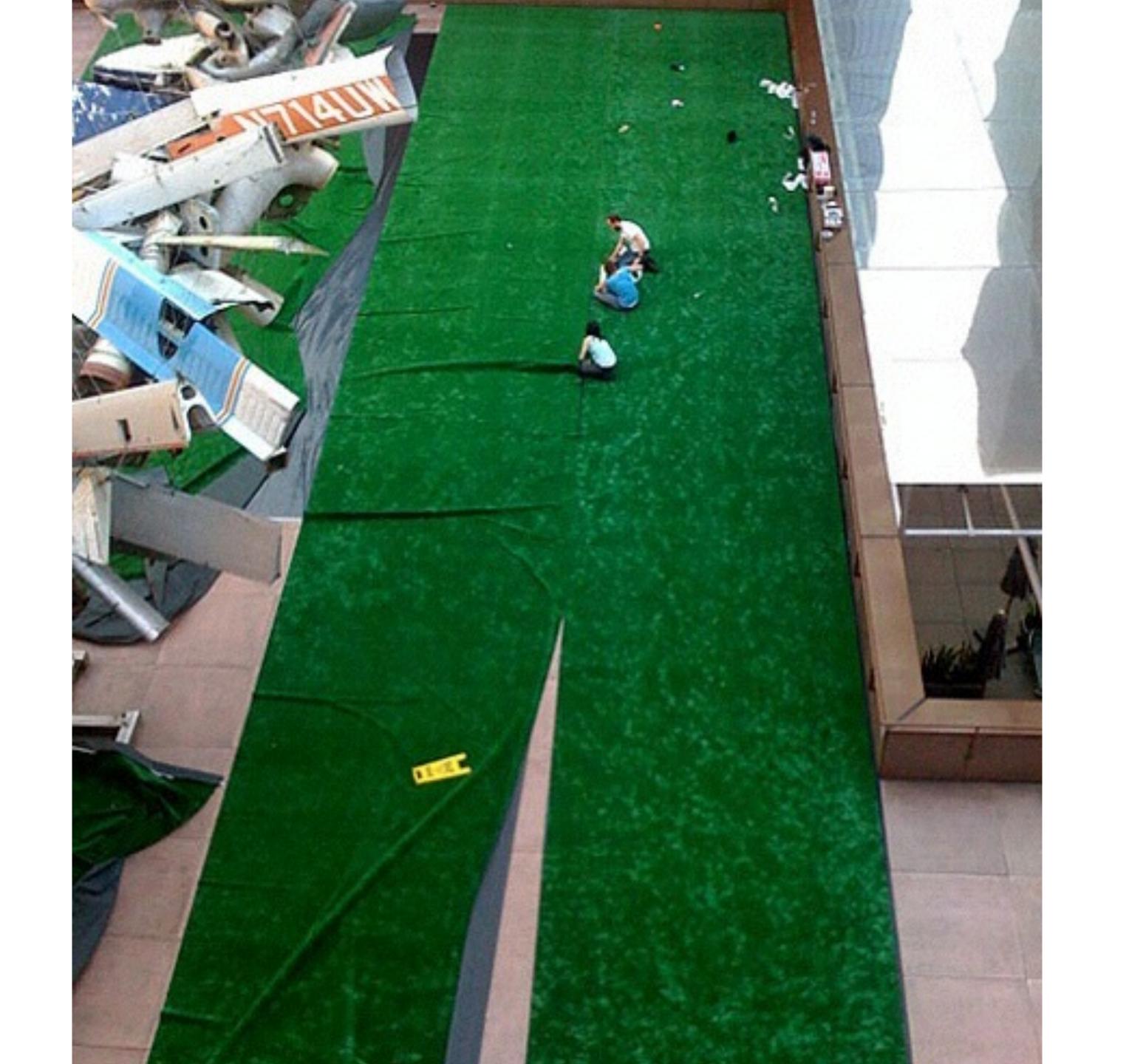








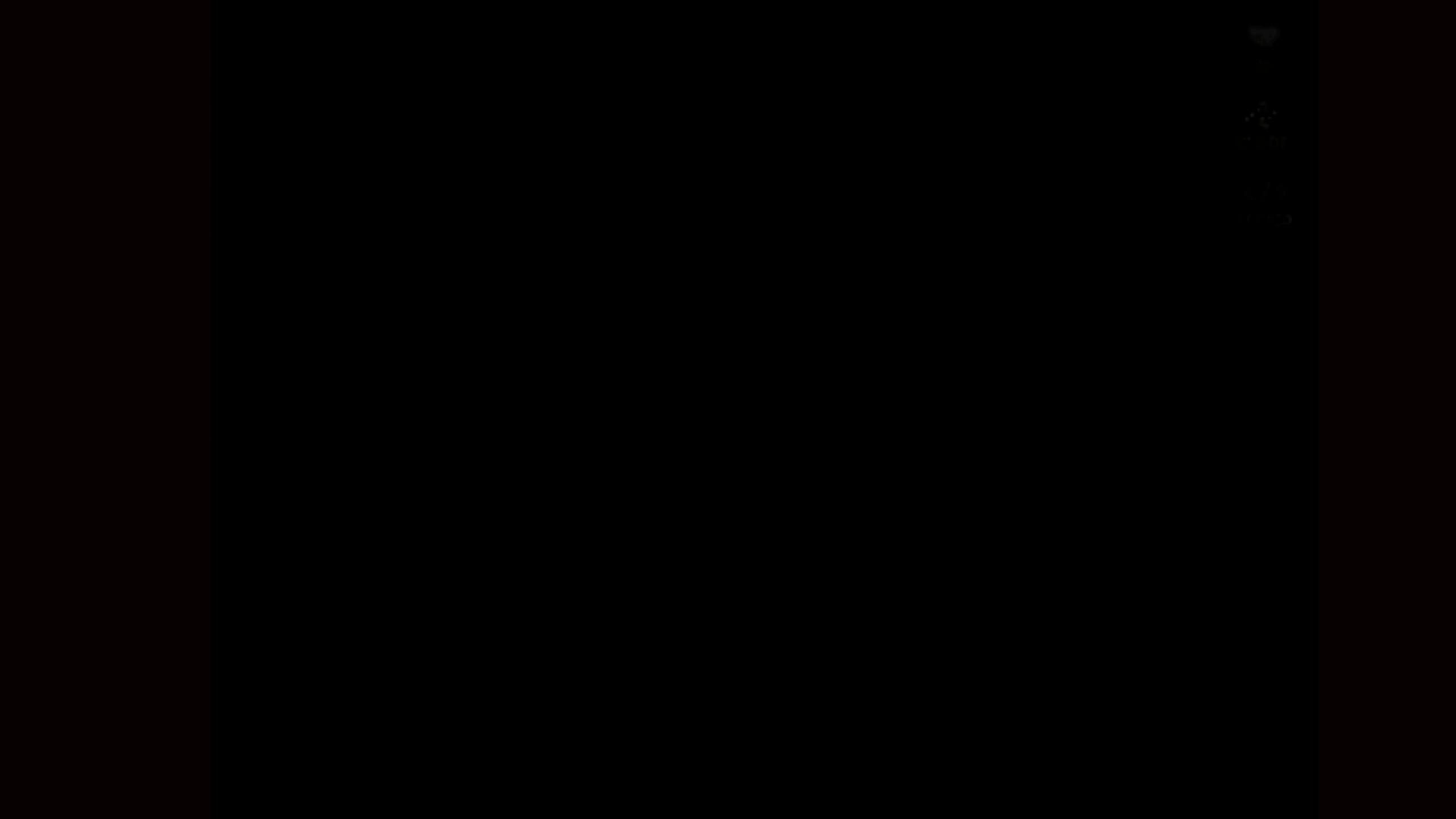
















choreography of humans, networks, and urban wildlife.

cyborg listening. machine-assisted listening. except not human-machine, but ecosystem-machine.

patience. waiting in theaters of conflict. war-time.

geologic time vs historical time. the long now, time compression / expansion.

the data center as temporal architecture. freezing time. temporal capacitors.

a rhythm database. rhythm sensors. the rhythmanalysis lab: <a href="http://rhythmanalysislab.org">http://rhythmanalysislab.org</a>

https://github.com/brianhouse/braid



# Thanks! @h0use http://brianhouse.net